

Introduction to Elliptic PDEs

Part II.

for online PDE coffee chat.

Mark Ma

Problem ③ Continued What have we done so far? for $0 < \alpha < 1$.

$$\begin{cases} \Delta u = f & \Omega \\ u = g & \partial\Omega \end{cases}$$

for $f \in C^{0,\alpha}$ compactly supported, $g \in C(\bar{\Omega})$, $\partial\Omega$ satisfying exterior ball condition.

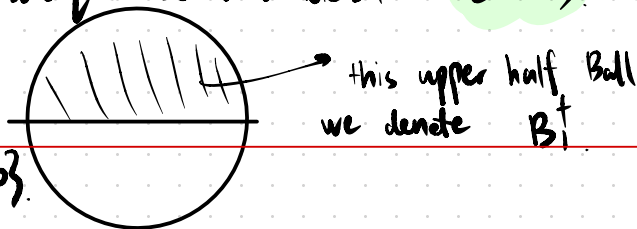
we've established $u \in C^2(\Omega) \cap C^{2,\alpha}(\bar{\Omega})$ unique solution

Moreover, using Singular integral approach, we gain interior $C^{2,\alpha}$ estimates.

Today we start with

Global Regularity and ask whether our unique solution lies in $C^{2,\alpha}(\bar{\Omega})$?

Step 1 Boundary Estimates on half Balls



Lemma let $u \in C^2(B_1^+) \cap C^0(\bar{B}_1^+)$, $u=0$ on $\{x_n=0\}$.

solve $\Delta u = f$ B_1^+ with $f \in C^{0,\alpha}(\bar{B}_1^+)$ with compact support in B_1 .

then we want estimate $\|u\|_{C^2(\bar{B}_{1/2}^+)} \leq C(n,\alpha) (\|u\|_{C^0(\bar{B}_1^+)} + \|f\|_{C^{0,\alpha}(\bar{B}_1^+)})$ (*)

All bad things happen because there could be "cut" in the force term.



our force f .

strategy: to extend force, Newtonian potential and Harmonic part.

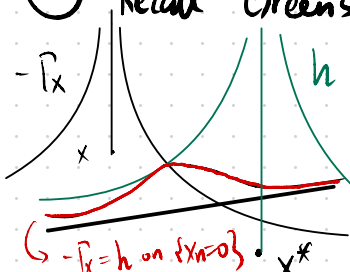
Morally we still want $u = w + v$, $w = \Gamma * f$, v harmonic function

Leverage $u=0$ on $\{x_n=0\}$. design \tilde{w} so $\tilde{w}=0$ on $\{x_n=0\}$. thus $\tilde{v} = u - \tilde{w} = 0$ on $\{x_n=0\}$

use Green's function

use Schwartz Reflection

① Recall Green's function $G_{\mathbb{R}_+^n}(x, y) = \Gamma_x(y) + h(y)$ where $\begin{cases} \Delta h = 0 & \mathbb{R}_+^n \\ h = -\Gamma_x & \{x_n=0\} \end{cases}$

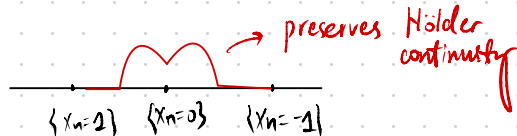


Define reflection point $x^* = (x_1, \dots, x_{n-1}, -x_n) \forall x \in \mathbb{R}_+^n$

then $G(x, y) = \Gamma_x(y) - \Gamma_{x^*}(y) = \Gamma(x-y) - \Gamma(x^*-y)$

Define $\tilde{w}(x) = \int_{B_1^+} G(x, y) f(y) dy$ so that $\tilde{w} = 0$ on $\{x_n=0\}$

② Reflect force evenly $\tilde{f}(x) = \begin{cases} f(x) & x \in B_1^+ \\ f(x' - x_n) & x \in B_1^- \end{cases}$



$\Rightarrow \tilde{w}(x) = \int_{B_1^+} (\Gamma(x-y) - \Gamma(x^*-y)) f(y) dy = \int_{B_1^+} (\Gamma(x-y) - \Gamma(x-y^*)) f(y) dy$

note $\int_{B_1^+} \Gamma(x-y^*) f(y) dy = \int_{B_1^-} \Gamma(x-y) \tilde{f}(y) dy$ use radial symmetry by change of variables

thus $\tilde{w}(x) = \int_{B_1^+} \Gamma(x-y) f(y) dy - \int_{B_1^-} \Gamma(x-y) \tilde{f}(y) dy = 2 \int_{B_1^+} \Gamma(x-y) f(y) dy - \int_{B_1^-} \Gamma(x-y) \tilde{f}(y) dy$

the above has two parts! $\tilde{f} \in C^{0,\alpha}(\mathbb{B}_1)$ so the second part has good estimate.
What about first part? let $\bar{w}(x) := \int_{\mathbb{B}_1^+} \tilde{T}(x-y) f(y) dy$.

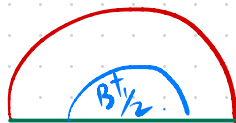
$$\partial_j \bar{w}(x) = \int_{\mathbb{B}_1^+} \partial_j \tilde{T}(x-y) (f(y) - f(x)) dy + f(x) \int_{\partial \mathbb{B}_1^+} \partial_i \tilde{T}(x-y) \nu_j dS(y)$$

To see second part,

We use divergence theorem $\int_{\mathbb{B}_1^+} \partial_j \tilde{T}(x-y) dy = \int_{\partial \mathbb{B}_1^+} \partial_i \tilde{T}(x-y) \nu_j dS(y)$ then send $\varepsilon \rightarrow 0$
 Note $\partial \mathbb{B}_1^+ = (\partial \mathbb{B}_1 \cap \mathbb{R}_+^n) \cup (\mathbb{B}_1 \cap \partial \mathbb{R}_+^n)$

Holder regularity ensure well-defined.

ν outward normal



$\mathbb{B}_1 \cap \partial \mathbb{R}_+^n$ is what matters.

this doesn't matter since stays $\frac{1}{2}$ distance away.

When $x \in \mathbb{B}_{\frac{1}{2}}^+$ (i) But $\nu_j|_{\partial \mathbb{R}_+^n} = 0 \quad \forall j \neq n$. Since $\nu = (0, \dots, 0, -1)$

\Rightarrow all mixed derivatives contribute 0 on $\partial \mathbb{R}_+^n$ and the estimate fully inherits from singular integral in \mathbb{B}_1^+ .

(ii) for pure normal derivative

$$\partial_{nn} \bar{w} = f - \sum_{i=1}^{n-1} \partial_{ii} \bar{w} \quad \text{use equation!}$$

$$\|\partial_{nn} \bar{w}\|_{C^{0,\alpha}(\bar{\mathbb{B}}_{\frac{1}{2}}^+)} \lesssim \|f\|_{C^{0,\alpha}} + \sum_{i=1}^{n-1} \|\partial_{ii} \bar{w}\|_{C^{0,\alpha}} \lesssim \|f\|_{C^{0,\alpha}}$$

To conclude for \tilde{w} .

$$\|\partial_j \tilde{w}\|_{C^{0,\alpha}(\bar{\mathbb{B}}_{\frac{1}{2}}^+)} \leq C(n,\alpha) \|f\|_{C^{0,\alpha}(\bar{\mathbb{B}}_1^+)}$$

③ for $v = u - \tilde{w}$ $\begin{cases} \Delta v = 0 & B_1^+ \\ v = 0 & B_1 \cap \{x_n = 0\} \end{cases}$ that $v=0$ ($x_n=0$) is crucial assumption for Schwarz reflection to preserve harmonicity

Schwarz Reflection extends v to \tilde{v} defined in B_1 s.t. $\begin{cases} \Delta \tilde{v} = 0 & B_1 \\ \tilde{v} = v & B_1^+ \end{cases}$
 $\tilde{v}(x) := \begin{cases} v(x) & x \in B_1^+ \\ -v(x', -x_n) & x \in B_1^- \end{cases}$ easily check MVP is satisfied on $\{x_n = 0\}$!

Now use gradient estimates for harmonic functions.

$$\|v\|_{C^{2,\alpha}(\overline{B_{1/2}^+})} \leq \|\tilde{v}\|_{C^{2,\alpha}(\overline{B_{1/2}})} \leq C(n,\alpha) \|\tilde{v}\|_{C(\overline{B_1})} \leq C(n,\alpha) (\|u\|_{C(\overline{B_1^+})} + \|f\|_{C(\overline{B_1})})$$

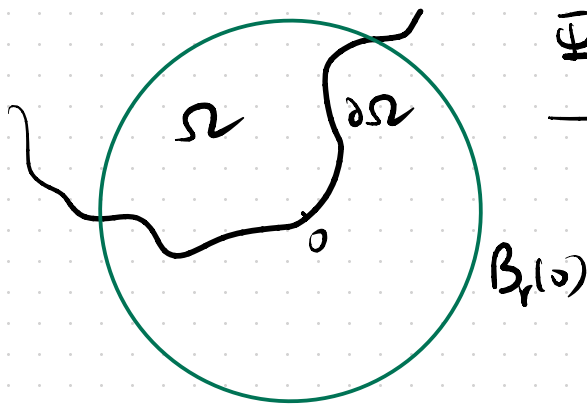
Finally, writing $u = \tilde{w} + \tilde{v}$ the desired estimate (*) follows \square

Now we have our boundary estimates on $\overline{B_{1/2}^+}$.

Can we conclude Global $C^{2,\alpha}$ regularity?

NOT NOW!

Assume our Ω is $C^{2,\alpha}$.



$\bar{\Psi} \in C^{2,\alpha}$ domain deformation.



$\bar{\Psi}(B_r(x_0) \cap \partial\Omega)$

Sure, this we can always do.
BUT our equation changes !!!

Say $y = \bar{\Psi}(x)$ $\bar{\Psi} \in C^{2,\alpha}$ local diffeomorphism.

then assume $\Delta u = f$ in Ω . define $\tilde{u}(y) = u(x)$, $\tilde{f}(y) = f(x)$

So $\partial_i u = \partial_k \tilde{u} \partial_i \bar{\Psi}^k$.

$\partial_{ij} u = \partial_k \partial_l \tilde{u} \partial_i \bar{\Psi}^k \partial_j \bar{\Psi}^l + \partial_k \tilde{u} \partial_{ij} \bar{\Psi}^k$

and \tilde{u} solves

$$\partial_i \bar{\Psi}^k \partial_j \bar{\Psi}^l \partial_k \tilde{u} + \Delta \bar{\Psi}^k \partial_k \tilde{u} = \tilde{f}$$

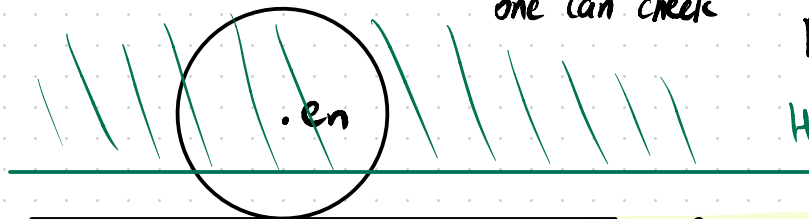
this is not Poisson's equation. and currently we can do nothing about it.

However we can solve on Balls.

Step 2: Global $C^{2,\alpha}$ Regularity on Balls

There is some special domain transformation Kelvin Transform that preserves the equation!

If $\Omega = B_1(e_n)$ consider $x \in B_1(e_n) \mapsto x^* = \frac{x}{|x|^2}$ reflection point.
 one can check $\{x_n > \frac{1}{2}\} = \{x^* \mid x \in B_1(e_n)\}$



Half plane is "Kelvin Transform" of unit Ball.

more over consider $u^*(x) := |x|^{2-n} u(x^*) \forall x_n > \frac{1}{2}$. (notice $(x^*)^* = x$)

one may check $\Delta u^* = |x|^{-n-2} f(x^*)$ still solves Poisson's equation in $\{x_n > \frac{1}{2}\}$
 provided $\Delta u = f$ in $B_1(e_n)$

Thus Lemma 1.

Boundary estimate on Half Ball applies

Problem 3.1 is solvable

$$\begin{cases} \Delta u = f & B_1 \\ u = g & \partial B_1 \end{cases} \quad \begin{matrix} f \in C^{0,\alpha}(\bar{B}_1), g \in C^{2,\alpha}(\bar{B}_1) \\ \exists! u \in C^{2,\alpha}(\bar{B}_1) \end{matrix} \quad (**)$$

with $\|u\|_{C^{2,\alpha}(\bar{B}_1)} \leq C(n,\alpha) (\|g\|_{C^{2,\alpha}} + \|f\|_{C^{0,\alpha}})$

Problem 4 a_{ij} uniformly elliptic, i.e., $\lambda |\xi|^2 \leq a_{ij} \xi_i \xi_j \leq \Lambda |\xi|^2 \quad \forall \xi \in \mathbb{R}^n$

$$\begin{cases} \mathcal{L}u = a_{ij} \partial_{ij} u + b_i \partial_i u + cu = f & \Omega \\ u = g & \partial\Omega \end{cases}$$

we always assume a_{ij} **unif. elliptic** with elliptic constants $0 < \lambda \leq \Lambda < \infty$

Theorem If $a_{ij}, b_i, c, f \in C^{0,\alpha}(\bar{\Omega})$, $g \in C^{2,\alpha}(\bar{\Omega})$, $\Omega \subset \mathbb{R}^n$ Domain, and **Maximum Principle** holds then $\exists!$ $u \in C^{2,\alpha}(\bar{\Omega})$ solution and $\|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq (C(n, \Omega, \alpha, \lambda, \Lambda)) (\|f\|_{C^{0,\alpha}(\bar{\Omega})} + \|g\|_{C^{2,\alpha}(\bar{\Omega})})$

Some immediate Remarks

- i) $\mathcal{L} = \Delta$ with $\Omega \subset \mathbb{R}^n$ is a special case, but solves **Problem 3** on general $C^{2,\alpha}$ domains.
- ii) to prove the theorem, we need the fact that **Problem 3** is solvable on Balls. The ingredient combines $\left\{ \begin{array}{l} \text{Method of Continuity} \\ \text{A priori Estimates.} \end{array} \right.$
- iii) that **Maximum Principle** needs to hold is essential!

• Method of Continuity let $L_0, L_1 : \underset{\text{Banach space}}{X} \rightarrow \underset{\text{normed vector space}}{Y}$ be bounded linear operators.

consider a family of operators

$$L_t := (1-t)L_0 + tL_1 : X \rightarrow Y$$

Assume that we know

- (i) $\|x\|_X \leq C \|L_t x\|_Y \quad \forall t \in [0, 1], \forall x \in X$
- (ii) L_0 is invertible, i.e., L_0 bijective, L_0^{-1} bounded linear.

Then L_1 is invertible.

proof What do we mean by L_t invertible? $\forall y \in Y, \exists! x \in X$ s.t. $L_t x = y$.

But $L_t x = y \Leftrightarrow L_0 x = y + t(L_0 - L_1)x$

$\Leftrightarrow x = \underbrace{L_0^{-1}y + t \cdot L_0^{-1}(L_0 - L_1)x}_{\text{Define as } Tx}$ By assumption (i) L_0 is invertible

\Rightarrow it suffices to show fixed point exists for T .
 Since X is Banach space we use Contraction Mapping Theorem. it suffices to show $\|T\| < 1$.

$\forall x_1, x_2 \in X, \|Tx_1 - Tx_2\|_X \leq t \cdot \|L_0^{-1}(L_0 - L_1)(x_1 - x_2)\|_X \stackrel{\text{(i) estimate on } L_0^{-1}}{\leq} C \cdot t \cdot \|(L_0 - L_1)(x_1 - x_2)\|_Y$

$\leq C \cdot t \cdot (\|L_0\| + \|L_1\|) \|x_1 - x_2\|_X < \|x_1 - x_2\|_X$

By taking $t < \frac{1}{2C(\|L_0\| + \|L_1\|)} =: \delta$ But this δ is uniform in $x \in X, t \in [0, 1] \Rightarrow$ push all the way to $t=1$

In practice, what are our X, Y, L_0, L_1 , and estimate (i)?

① up to subtracting $u-g$, we treat $Lg \in C^{0,\alpha}(\bar{\Omega})$ as force. Hence WLOG, assume $u=0$ on $\partial\Omega$

Define $X := C_{zero}^{2,\alpha}(\bar{\Omega}) = \{u \in C^{2,\alpha}(\bar{\Omega}) \mid u=0 \text{ on } \partial\Omega\}$. $Y := C^{0,\alpha}(\bar{\Omega})$

② $L_0 = \Delta$ Laplace operator is our most natural choice.

$L_1 = \mathcal{L}$ non-divergence form uniformly elliptic operator is our target.

③ What's missing to apply Method of continuity?

(i) A priori Estimates. $\|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq C \|L_t u\|_{C^{0,\alpha}(\bar{\Omega})} \quad \forall t \in [0,1], \forall u \in C_{zero}^{2,\alpha}(\bar{\Omega})$

part of our assumption
Reason it's called
"A priori"

Recall $L_t = (1-t)L_0 + tL_1$. So we're really looking for estimates.

for u solution to either $\begin{cases} \Delta u = f & \Omega \\ u = 0 & \partial\Omega \end{cases}$ that $\|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq C (\|u\|_{C^0(\bar{\Omega})} + \|f\|_{C^{0,\alpha}(\bar{\Omega})})$

$\leq C \|f\|_{C^{0,\alpha}(\bar{\Omega})}$
requires maximum principle.

(ii) Invertibility of $L_0 = \Delta$

we've solved Problem ③ on Balls. But we haven't done so for general Domains.

A priori Estimates \rightarrow part of the assumption!

Theorem Let $u \in C^{2,\alpha}(\bar{\Omega})$ be solution to $\mathcal{L}u = a_{ij} \partial_{ij} u + b_i \partial_i u + cu = f$ $\Omega \in C^{2,\alpha}$
with a_{ij} unif. elliptic, and $a_{ij}, b_i, c, f \in C^{0,\alpha}(\bar{\Omega})$.
Then $\exists C = C(n, \alpha, \Omega, \text{data}) > 0$ s.t.
$$\|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq C (\|u\|_{C^0(\bar{\Omega})} + \|f\|_{C^{0,\alpha}(\bar{\Omega})})$$

notice we do not assume for maximum principle.

Let's only prove for the interior version. **Method of Freezing Coefficients.**

Lemma Let $u \in C^2(\bar{B}_1)$ solve $a_{ij} \partial_{ij} u + b_i \partial_i u + cu = f$ B_1 , a_{ij} unif. elliptic, $\text{data} \in C^{0,\alpha}(\bar{B}_1)$
then $\exists \delta = \delta(n, \alpha) > 0$ small, and $C = C(n, \alpha, \Omega) > 0$
s.t. whenever $\|a_{ij} - \delta_{ij}\|_{C^{0,\alpha}}, \|b_i\|_{C^{0,\alpha}}, \|c\|_{C^{0,\alpha}} \leq \delta$ (*)
one has $\|u\|_{C^{2,\alpha}(\bar{B}_{1/2})} \leq C (\|u\|_{L^\infty(B_1)} + \|f\|_{C^{0,\alpha}(\bar{B}_1)})$

(*) is to assume our operator \mathcal{L} is "small perturbation" of Laplace

↳ Hence the estimate should "morally" look the same as that of Laplace's.
↳ Why makes sense to assume? By rescaling! $u_r(x) = u(rx) \quad \forall x \in B_1$

proof WLOG assume $a_{ij}(0) = \delta_{ij}$ then

$$a_{ij}(0)\partial_{ij}u = \underbrace{(a_{ij}(0) - a_{ij})\partial_{ij}u - b_i \partial_i u - cu + f}_{= F}$$

this takes the form of Poisson's equation!

so estimate for Laplace writes

$$\begin{aligned} \|u\|_{C^{2,\alpha}(\bar{B}_{1/2})} &\leq C(\|u\|_{C^0(\bar{B}_{3/4})} + \|F\|_{C^{0,\alpha}(\bar{B}_{3/4})}) \\ &\leq C(\|u\|_{C^0} + \underbrace{\|a_{ij} - \delta_{ij}\|_{C^{0,\alpha}}}_{\leq \delta} \|\partial_{ij}u\|_{C^{0,\alpha}} + \underbrace{\|b_i\|_{C^{0,\alpha}}}_{\leq \delta} \|\partial_i u\|_{C^{0,\alpha}} + \underbrace{\|c\|_{C^{0,\alpha}}}_{\leq \delta} \|u\|_{C^{0,\alpha}} + \|f\|_{C^{0,\alpha}}) \end{aligned}$$

In fact, this step uses assumption $u \in C^{2,\alpha}$

Recall Interpolation for Hölder Spaces. $\forall \varepsilon > 0, \exists C(\varepsilon) > 0$ s.t.

$$\|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq C(\varepsilon) \|u\|_{C^0(\bar{\Omega})} + \varepsilon \|D^2 u\|_{C^{0,\alpha}(\bar{\Omega})}$$

$$\text{so } \|D^2 u\|_{C^{0,\alpha}(\bar{B}_{1/2})} \leq C(\|u\|_{C^0} + \|f\|_{C^{0,\alpha}}) + (\delta \|D^2 u\|_{C^{0,\alpha}(\bar{B}_{3/4})}) \quad (\Delta)$$

it is very annoying that the domain on RHS is larger
so we cannot simply absorb.

We can use a trick.

$$\|D^2 u\|_{C^{0,\alpha}(\bar{B}_{1/4})} \leq (Cn) \sup_{B_{1/8}(x) \subseteq B_{3/4}} \|D^2 u\|_{C^{0,\alpha}(\bar{B}_{1/8}(x))}$$

shrink the domain on RHS, at the cost of "recentering".

We WLOG assume $\|u\|_{C^0(\bar{B}_1)} + \|f\|_{C^{0,\alpha}(\bar{B}_1)} \leq 1$. By dividing by large constant.

Rescaling

$u_r(x) := u(rx) \quad \forall x \in B_1$ we ask how equation u_r solves hitting derivatives on $u_r(\frac{x}{r}) = u(x) \quad \forall x \in B_r$ and use $Lu = f$ B_r to obtain that

$$a_{ij}(rx) \partial_j u_r + r b_i(rx) \partial_i u_r + r^2 c(rx) u_r = r^2 f(rx) \quad B_1$$

my coefficients still satisfy (A) upon choosing r sufficiently small.

now what happens if I bring my u_r into (Δ) ?

$$r^{2+\alpha} [D^2 u]_{C^0(\overline{B_{r/2}})} \leq C \left(\|u\|_{C^0(\overline{B_{3r/4}})} + r^{2+\alpha} \|f\|_{C^0(\overline{B_{3r/4}})} \right) + \underbrace{C \cdot \delta}_{\mu} \cdot r^{2+\alpha} \sup_{B_{r/8}(x) \subseteq B_{3r/4}} [D^2 u]_{C^0(\overline{B_{r/8}(x)})}$$

$$\Rightarrow [D^2 u]_{C^0(\overline{B_{r/2}(0)})} \leq C \cdot r^{-3} + \mu [D^2 u]_{C^0(\overline{B_{r/8}(x)})} \text{ for some } B_{r/8}(x) \subseteq B_{3r/4}(0)$$

Refine sequence $x_0 = 0$.

$$\left\{ \begin{array}{l} r_k = \frac{1}{2} \cdot \frac{1}{2^{2k}} \\ B_{r_{k+1}}(x_{k+1}) \subseteq B_{3r_k/2}(x_k) \end{array} \right. \quad \forall k \geq 0$$

$$\forall k \geq 1$$

where $[D^2 u]_{C^0(\overline{B_{r_{k+1}}}(x_{k+1}))}$ achieves sup

Refine $a_k := [D^2 u]_{C^0(\overline{B_{r_k}(x_k)})}$

then we obtain

$$a_k \leq M \cdot 2^{6k} + \mu \cdot a_{k+1} \quad \forall k \geq 0$$

Recall our goal is to show $\exists \mu$ small, $C > 0$ universal

s.t.

$$a_0 \leq C \text{ uniformly in } u \in C^{2,\alpha}(B_1).$$

Assume for contradiction

$a_0 > C$ for C of our choice.

- Base case satisfied then $a_k > C \delta^k$ for $\delta > 1$ universal
- assume for k $a_{k+1} \geq \frac{1}{\mu} (a_k - M \cdot 2^{6k})$

$$\boxed{\geq} \frac{1}{\mu} (C \delta^k - M 2^{6k}) \quad \text{inductive hypothesis} \quad \text{want to ensure} \quad > C \delta^{k+1}$$

pick for example $\mu = 2^{-7}$
 $\delta \in [2^6, 2^7)$

choose $C > \frac{M}{1 - \mu \delta}$ sufficiently large

so that $\lim_{k \rightarrow \infty} a_k = \infty$.

But the limiting point $x_\infty = \lim_{k \rightarrow \infty} x_k \in B_{1/2}$ up to subsequences. Reach contradiction that $u \in C^{2,\alpha}(B_1)$ \square

- Boundary a priori estimates follows same procedure from Boundary $C^{2,\alpha}$ estimate for Poisson's Equation on half Balls.
 - Global a priori estimates follow by covering with balls and that the class of uniformly elliptic non-divergence form equations with $C^{0,\alpha}$ coefficients remains invariant under $C^{2,\alpha}$ Domain Deformations.
- This concludes the proof of Global A priori Schauder estimates
-

OK But now. What about **Invertibility of $L_0 = \Delta$?**

With the help of **a priori estimates** + **method of continuity** + **Problem (3.2) solvable**

We solve **Problem (4.1)**
$$\begin{cases} Lu = a_{ij} \partial_{ij} u + b_i \partial_i u + cu = f & B_1 \\ u = g & \partial B_1 \end{cases}$$

if $C^{0,\alpha}$ coefficients and maximum principle holds

$\exists ! u \in C^{2,\alpha}(\bar{B}_1)$ with $\|u\|_{C^{2,\alpha}(\bar{B}_1)} \leq C(n, \alpha, \lambda, \Lambda) (\|f\|_{C^{0,\alpha}(\bar{B}_1)} + \|g\|_{C^{2,\alpha}(\partial B_1)})$

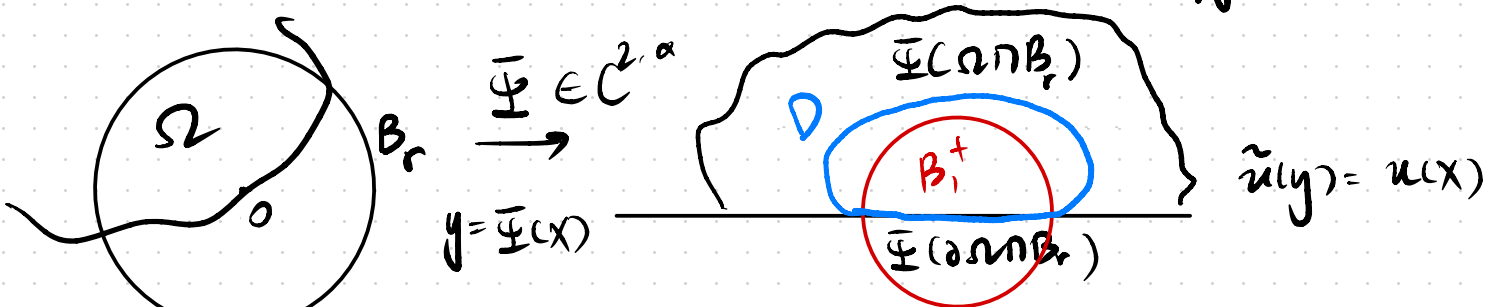
Now what about general domains Ω that are $C^{2,\alpha}$?

It suffices to ensure $L_0 = \Delta$ is invertible, i.e., for $f \in C^{0,\alpha}(\bar{\Omega})$, $g \in C^{2,\alpha}(\bar{\Omega})$

$$\begin{cases} \Delta u = f & \Omega \\ u = g & \partial\Omega \end{cases} \exists! u \in C^{2,\alpha}(\bar{\Omega}) \text{ s.t. } \|u\|_{C^{2,\alpha}(\bar{\Omega})} \leq C \left(\|f\|_{C^{0,\alpha}(\bar{\Omega})} + \|g\|_{C^{2,\alpha}(\bar{\Omega})} \right)$$

In other words it suffices to solve **Problem 3** completely.

What do we have? $u \in C^{2,\alpha}(\Omega) \cap C^0(\bar{\Omega})$ need to upgrade to **Global $C^{2,\alpha}$**



\tilde{u} solves $\tilde{L} \tilde{u} := \partial_i \tilde{\Phi}^k \partial_i \tilde{\Phi}^l \partial_{kl} \tilde{u} + \Delta \tilde{\Phi}^k \partial_k \tilde{u} = \tilde{f}$ in B_1^+

But what is Boundary Data \tilde{u} on ∂B_1^+ ?

We assume only $\tilde{u} \in C^2(B_1^+) \cap C^0(\bar{B}_1^+)$

Claim 1 One may solve $\begin{cases} \mathcal{L}u = f & D \\ u = g & \partial D \end{cases}$ for $D \subset \mathbb{C}^{2, \alpha}$ D diffeomorphic to a Ball.

Problem (4.2)

this can be done directly with the help of

a priori estimates + Method of continuity +

$L_0 = \Delta$ invertible on D

this is resolved due to Problem (4.1) is solvable

Claim 2 take D as such domain diffeomorphic to Balls that covers B_1^+

By our assumption \tilde{u} is only continuous up to ∂D call $\varphi = \tilde{u}|_{\partial D}$

Now approximate $\{\varphi_k\} \in C^{2, \alpha}(\bar{D})$ boundary data that is uniformly bounded $C^2(\bar{D})$

s.t. $\|\varphi_k - \varphi\|_{C^0(\partial D)} \rightarrow 0$

for each φ_k solve \tilde{u}_k

$$\begin{cases} \mathcal{L} \tilde{u}_k = f & D \\ \tilde{u}_k = \varphi_k & \partial D \end{cases}$$

$\Rightarrow \exists! \tilde{u}_k \in C^{2, \alpha}(\bar{D})$

this is solvable because Problem (4.2) is solvable.

with $\|\tilde{u}_k\|_{C^{2, \alpha}(\bar{D})} \leq C \left(\|f\|_{C^{2, \alpha}} + \|\varphi_k\|_{C^2(\bar{D})} \right)$ (*)

Now, what about this family of $\{\tilde{u}_k\} \in C^{2,\alpha}(\bar{D})$?

•
$$\begin{cases} \tilde{L}(\tilde{u}_k - \tilde{u}_\ell) = 0 \\ \tilde{u}_k - \tilde{u}_\ell = \varphi_k - \varphi_\ell \end{cases} \quad \text{By Maximum Principle}$$

$$\|\tilde{u}_k - \tilde{u}_\ell\|_{C(\bar{D})} \leq \|\varphi_k - \varphi_\ell\|_{C(\bar{D})} \rightarrow 0$$

thus $\exists ! \tilde{u} \in C(\bar{D})$ s.t. $\|\tilde{u}_k - \tilde{u}\|_{C(\bar{D})} \rightarrow 0$,
 which of course coincides with our original \tilde{u} .

• But one also has the Estimates (★)

$$\|\tilde{u}_k\|_{C^{2,\alpha}(\bar{D})} \leq C \quad \text{uniformly bounded in } k.$$

Now by **Ascoli-Arzelà** the limit $\tilde{u} \in C^{2,\alpha}(\bar{D})$

In particular $B_1 \cap \{x_n = 0\} \subseteq \partial D$.

$$\text{So } \|\tilde{u}\|_{C^{2,\alpha}(\bar{B}_{1/2}^+)} \leq C(n, \alpha, \Phi, \text{data}) \left(\|\tilde{f}\|_{C(\bar{B}_1^+)} + \|\tilde{g}\|_{C(\bar{B}_1^+)} \right)$$

With the Boundary estimates one may go to Global $C^{2,\alpha}$ estimates

⇒ Problem (3) is solvable for $u \in C^{2,\alpha}(\bar{\Omega})$

⇒ Problem (4) is solvable for $u \in C^{2,\alpha}(\bar{\Omega})$

using a priori estimate + method of continuity + Problem (3) solvable



A Remark on importance of Maximum Principle.

consider for example
$$\begin{cases} u'' + u = 0 & (0, \pi) \\ u(0) = 0 \\ u(\pi) = 1 \end{cases}$$

general solution takes the form $u(t) = A \sin(t) + B \cos(t)$

But $u(0) = B = 0$

$u(\pi) = -B = 1$

contradiction.

⇒ NO solution to this Dirichlet Problem.

Maximum Principle holds in general when $C \leq 0$ or for some $C_0 = C_0(n, \alpha, \Omega) > 0, C \leq C_0$