

Introduction to Elliptic PDEs

Part I.

for online PDE coffee chat

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Agenda We'll talk about the "Dirichlet Problem" for

① Laplace Equation

② Poisson's Equation

• What is ellipticity?

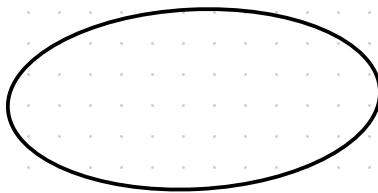
Suppose one is given matrix $A = (a_{ij})$. What does $\{x \in \mathbb{R}^n \mid x^T A x = 1\}$ look like in \mathbb{R}^n ?

since $x^T A x = x^T (\frac{1}{2}(A + A^T)) x$ it suffices to consider for A symmetric.

Say $n=2$. $(x, y) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = ax^2 + 2bxy + cy^2 = 1$

if $\det(A) = ac - b^2 > 0$

then



this is your set.

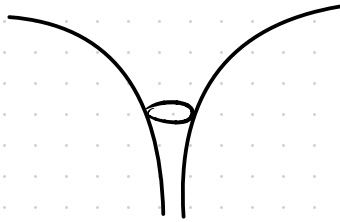
- In general, ellipticity refers to positivity of the leading order coefficient matrix $A = (a_{ij})$

- Simplest Example is $\Delta u = 0$ - Laplace Equation

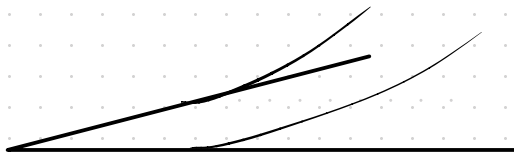
What are some solutions?

- any linear functions
- fundamental solution

$$\bar{T}(x) = \begin{cases} c_n |x|^{2-n} & n \geq 3 \\ c_n \log |x| & n = 2 \end{cases}$$



- cone solutions



they're radial global solutions to $\Delta \bar{T} = 0$ except at 0.
 obtained by solving $\frac{\partial^2}{\partial r^2} u + \frac{n-1}{r} \frac{\partial}{\partial r} u + \frac{1}{r^2} \Delta_{S^{n-1}} u = 0$
 and assuming for $u(x) = \bar{T}(x)$.

$$\begin{aligned} f(r, \theta) &= r^\alpha \cos(\alpha \theta) \quad -\frac{\pi}{2} \leq \alpha \theta \leq \frac{\pi}{2} \\ &= \operatorname{Re}(z^\alpha) \end{aligned}$$

Some Key Properties for $u \in C^2(\Omega)$ to $\Delta u = 0$.

① mean value property $u(x) = \int_{B_r(x)} u \, dy = \int_{\partial B_r(x)} u \, d\hat{n}(y)$

this is "iff" for harmonic functions.

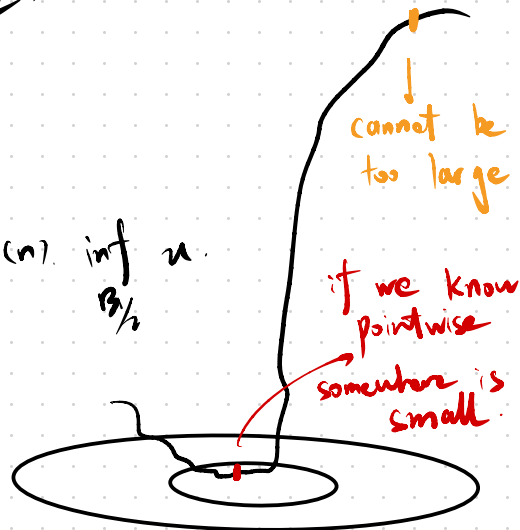
too good to wish for
for general elliptic PDEs.

② Maximum Principle

$$\begin{cases} \Delta u \geq 0 & \Omega \text{ bounded} \\ u \leq 0 & \partial\Omega \end{cases} \Rightarrow u \leq 0 \text{ in } \Omega$$

③ Harnack Inequality

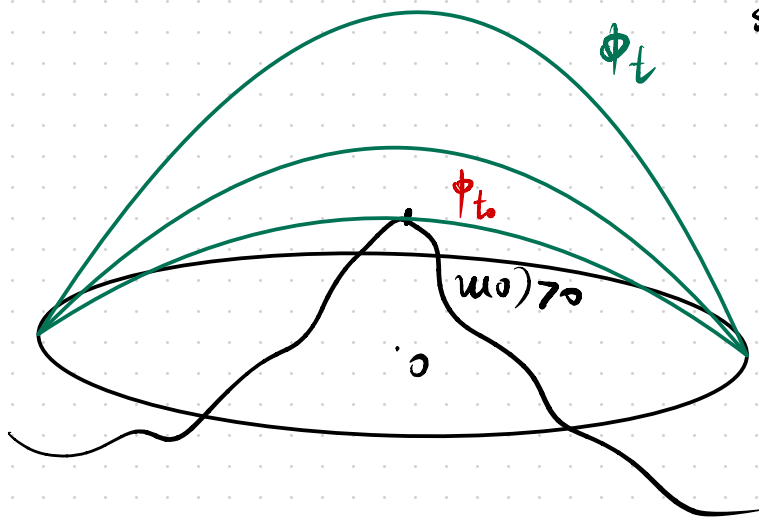
$$\begin{cases} \Delta u = 0 & B_1 \\ u > 0 & B_1 \end{cases} \Rightarrow \sup_{B_{1/2}} u \leq C \inf_{B_{1/2}} u$$



A Quick Proof for Maximum Principle without MVP

$$\left\{ \begin{array}{l} \Delta u \geq 0 \quad B_1 \\ u \leq 0 \quad \partial B_1 \end{array} \right\} \Rightarrow u \leq 0 \quad B_1$$

Proof assume at some $0 \in B_1$, $u(0) > 0$. the construct a family of barriers $\phi_t(x) = t(1 - |x|^2)$. note $\Delta \phi_t = -2nt < 0$



since $\phi_t \geq u$ on ∂B_1

at some $t_0 > 0$.

$$\left\{ \begin{array}{l} \phi_{t_0}(0) = u(0) \\ \phi_{t_0} \geq u \quad B_1 \end{array} \right.$$

$\Rightarrow \phi_{t_0} - u$ has interior local minimum.

$\Rightarrow \Delta(\phi_{t_0} - u) \geq 0$

But $0 \leq \Delta u \leq \Delta \phi_{t_0} = -2nt_0 < 0$

Contradiction!

□

• In this talk we study Dirichlet Problem which asks the following

- Given an equation
- Given a region where this equation is satisfied
- Given Boundary Data

⇒

① Existence & Uniqueness

Can I "solve" the equation?

If so, "solve" in what sense? Is the solution unique?

② Interior Regularity

How "smooth" can my solution become in the interior?

③ Boundary Regularity

If my boundary data is sufficiently smooth, can my solution approach the boundary data as smooth?

Or even more

④ Higher Regularity

If my coefficients, domain and boundary data are "smooth enough",
Does my solution inherit the smoothness?

⑤ If I cannot solve the problem.

Can I say something about when this happens?

Problem ①

Dirichlet Problem for $\Delta u = 0$ on Balls.

$$\begin{cases} \Delta u = 0 & B_1 \\ u = g & \partial B_1 \end{cases}$$

Method to solve

Poisson's Integral formula. $u(x) = (1 - |x|^2) \int_{\partial B_1} \frac{g(y)}{|x-y|^n} dH^{n-1}(y)$

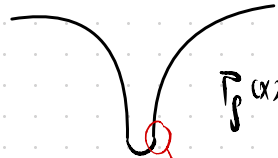
A formal derivation: for u, v smooth, Ω nice.

$$\int_{\Omega} \Delta u \cdot v = - \int_{\Omega} \nabla u \cdot \nabla v + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} v \, dS$$

assume $\Delta u = 0 \Rightarrow \int_{\Omega} u \Delta v + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} v \, dS - \int_{\partial \Omega} u \frac{\partial v}{\partial \nu} \, dS$

Choose $v = P_f$ let $f \rightarrow 0$.

$$\rightarrow 0 = \int_{\Omega} u \Delta P + \int_{\partial \Omega} \frac{\partial u}{\partial \nu} P \, dS - \int_{\partial \Omega} u \frac{\partial P}{\partial \nu} \, dS$$



$$P_f(x) = \begin{cases} P(x) & |x| \geq f \\ C^2 \text{ polynomial} & |x| < f \end{cases} \Rightarrow \text{with } P \text{ pole centered at } x_0 \in \Omega.$$

designed so $\Delta P_f = \frac{1}{|B_f|} \chi_{B_f}$ this recovers $\Rightarrow \Delta P_f \rightarrow \delta_0$ as $f \rightarrow 0$.

$$u(x_0) = \int_{\partial \Omega} u \frac{\partial P}{\partial \nu} \Big|_{x_0} \, dS - \int_{\partial \Omega} \frac{\partial u}{\partial \nu} P \Big|_{x_0} \, dS \quad (*)$$

But we want to solve the "Dirichlet problem".

we know $u|_{\partial\Omega}$ But not $\frac{\partial u}{\partial \nu}|_{\partial\Omega}$

Can I redesign and get rid of this?

YES! we introduce **Green's function** $G_{x_0}(y) := \Gamma_{x_0}(y) + h_{x_0}(y)$

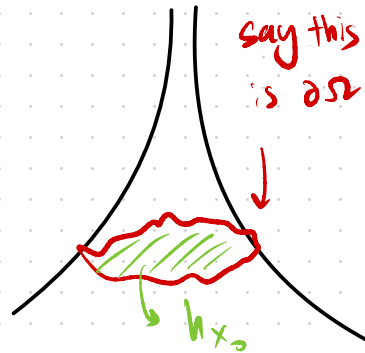
where h_{x_0} is harmonic replacement

$$\begin{cases} \Delta h_{x_0} = 0 & \text{in } \Omega \\ h_{x_0} = -\Gamma_{x_0} & \text{on } \partial\Omega \end{cases}$$

If such " h_{x_0} " exists for Ω

then (*) writes

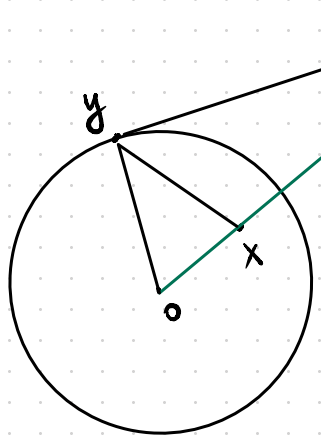
$$u(x_0) = \int_{\partial\Omega} u(y) \frac{\partial G_{x_0}(y)}{\partial \nu}(y) dS(y) \quad \text{Green's Representation}$$



Good News! for $\Omega = B_1$ one is able to find h_{x_0} !

How? By reflecting the pole outside B_1 .

We ask How to construct a harmonic function in B_1 that has boundary data $-P_{x_0}$ on ∂B_1 ?



$x^* := \frac{x}{|x|^2}$ reflect so that

Recall $\bar{P}_{x_0} = C_n |y - x_0|^{2-n}$

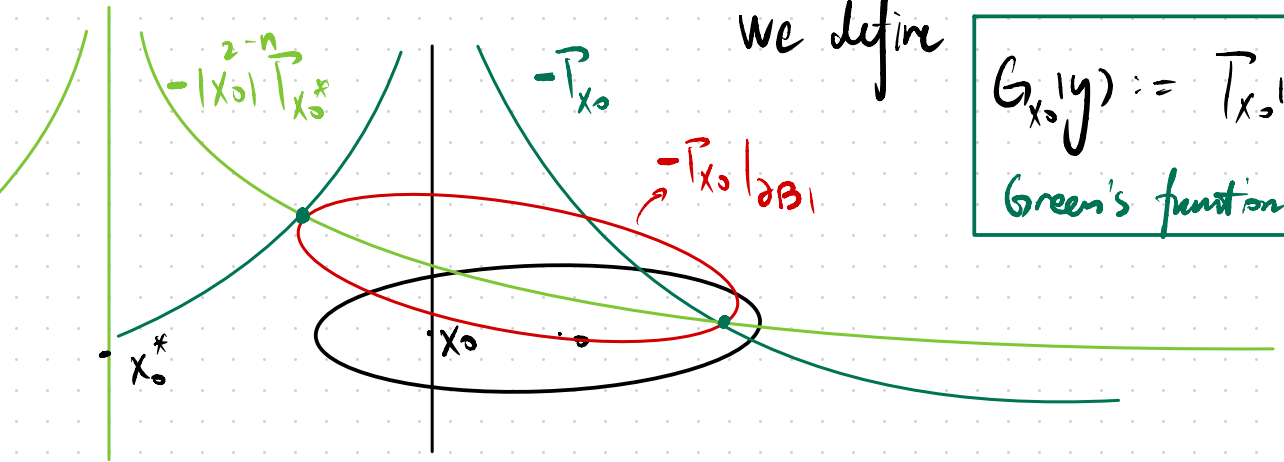
$\Delta y_0 x \simeq \Delta x^* o y$

i.e., $\frac{|x^* - y|}{1} = \frac{|y - x|}{|x|} \quad \forall y \in \partial B_1$

Now design $h_{x_0} := -|x_0|^{2-n} \bar{P}_{x_0^*}(y)$

We define

$G_{x_0}(y) := \bar{P}_{x_0}(y) - |x_0|^{2-n} \bar{P}_{x_0^*}(y)$
Green's function for B_1



look at the Green's Kernel $\Delta(y) = \frac{1}{|y|}$ outwards normal on B_1

$$\frac{\partial G}{\partial \nu_y} x_0(y) = \frac{1}{n \omega_n} \frac{1 - |x_0|^2}{|x_0 - y|^n}$$

Hence we construct Poisson's Integral formula $u(x_0) = (1 - |x_0|^2) \int_{\partial B_1} \frac{g(y)}{|x_0 - y|^n} d\mu^{n-1}(y)$

Interior Regularity Can we differentiate in x_0 ?

even in general, yes! can check that $G_{x_0}(y) = G_y(x_0)$

thus for any $y \in \partial B_1$, $\Delta_{x_0} G_y(x_0) = 0$

thus using Dominated Convergence theorem.

$$\Delta u(x_0) = 0 \quad \forall x_0 \in B_1$$

\Rightarrow By mean value property we know $u \in C^\infty(B_1)$

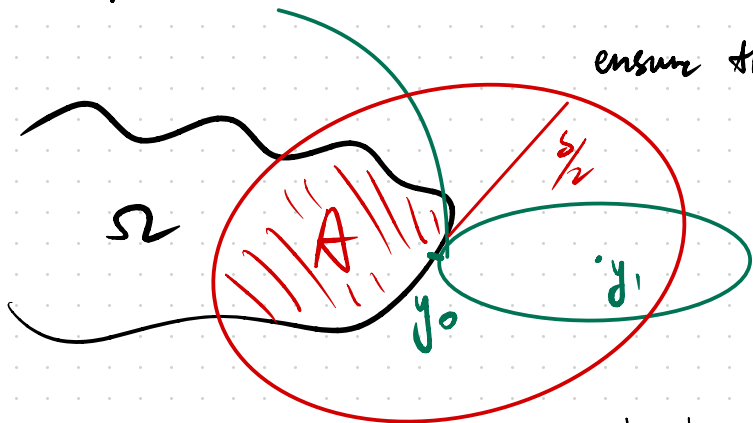
Green's function is symmetric.

Continuously Approach Boundary Data

Assume $g \in C(\partial\Omega)$

Can I show that $u(x) = \int_{\partial\Omega} g(y) \frac{\partial G}{\partial \nu}(x|y) dA^{n-1}(y)$ continuously approach g ?

If $\partial\Omega$ has exterior Ball condition, then yes!



ensure that $\forall \delta > 0, \sup_{|y-y_0| \geq \delta} \frac{\partial G}{\partial \nu}(x) \xrightarrow{x \rightarrow y_0} 0$

One may design Barrier w_{y_1} that satisfies

$$\begin{cases} \Delta w_{y_1} \leq 0 & \text{A} \\ w_{y_1}(y_0) = 0 \\ w_{y_1} \geq 0 & \text{A} \end{cases}$$

$$A = B_{\frac{r}{2}}(y_0) \cap \Omega$$

to trap boundary data $\frac{\partial G}{\partial \nu}(x) \leq w_{y_1}(x) \quad \forall x \in \partial A$

Now since $\frac{\partial G}{\partial \nu}$ is harmonic and w_{y_1} is super harmonic

\Rightarrow By Maximum Principle

$\forall |y-y_0| \geq \delta, y_0 \in \partial B_1$

$$\sup_{|y-y_0| \geq \delta} \frac{\partial G}{\partial \nu}(x) \leq w_{y_1}(x) \quad \forall x \in A$$

Send $x \rightarrow y_0$.

Why bother doing the above? use $\int_{\partial\Omega} \frac{\partial G}{\partial \nu} \times \nu \, dS(y) = 1$

$$|u(x) - g(x_0)| = \left| \int_{\partial\Omega} (g(x) - g(x_0)) \frac{\partial G}{\partial \nu} \times \nu \, dS(y) \right|$$

$$\leq \int_{|y-x_0| \leq \delta} |g(x) - g(x_0)| \left| \frac{\partial G}{\partial \nu} \right| + \int_{|y-x_0| > \delta} |g(x) - g(x_0)| \left| \frac{\partial G}{\partial \nu} \right|$$

\downarrow $\% g \in C(\partial B_1)$

\downarrow
due to uniform convergence
outside δ -neighborhood.

$\Rightarrow \rightarrow 0$ as $x \rightarrow x_0$.

Thus we conclude $u \in C^\infty(B_1) \cap C^0(\bar{B}_1)$

Uniqueness

Do I have uniqueness?

Yes. By B_1 is hdd domain & maximum principle

Problem ②

Dirichlet Problem for $\Delta u = 0$ on Ω
with exterior Ball condition

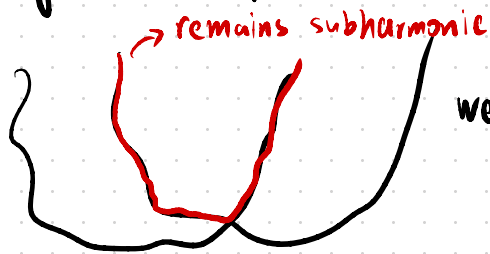
$$\begin{cases} \Delta u = 0 & \Omega \\ u = g & \partial\Omega \end{cases}$$

for example, $\Omega \in C^2$ has exterior ball condition.

Method to solve

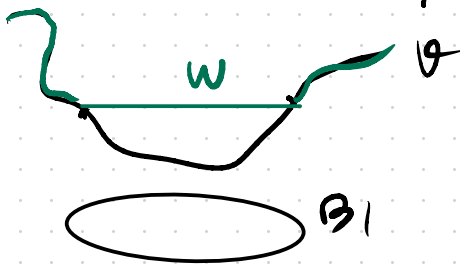
$$\text{Perron's Method } u(x) := \sup \left\{ v(x) \mid \begin{array}{l} v \leq g \text{ on } \partial\Omega \\ v \text{ subharmonic in } \Omega \\ v \in C(\bar{\Omega}) \end{array} \right\}$$

key important fact: subharmonic functions remain subharmonic upon taking maximum.



we also define harmonic lifting W for any v s.t. $\Delta v \geq 0$.

$$\text{as } \begin{cases} \Delta W = 0 & B_1 \\ W = v & \partial B_1 \end{cases} \rightarrow \text{this is solvable due to our Problem ①}$$



use MVP one can see $v \leq W$ in B_1
thus $\max\{u, v\}$ over $\Omega \supseteq B_1$
remains subharmonic function.

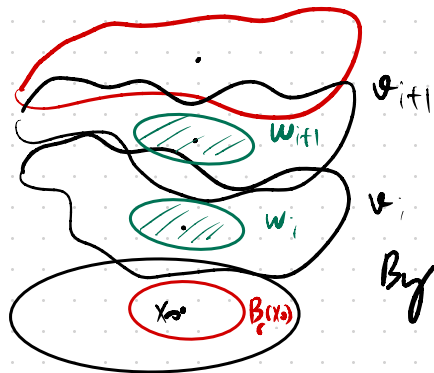
Claim $u(x)$ is harmonic in $\Omega \Rightarrow u \in C(\bar{\Omega})$ interior regularity these constants are subharmonic

first of all, the admissible set is nonempty because $m := \inf_{\Omega} g \leq v \leq M := \sup_{\Omega} g$

Due to definition via "sup" one may take "maximizing sequence" to u .

Pick any $x_0 \in \Omega$ and $B_r(x_0) \subset \Omega$. Choose $\{v_i\}$ admissible s.t. $\lim_{i \rightarrow \infty} v_i(x_0) = u(x_0)$

take $\{w_i\}$ as harmonic lifting of v_i in $B_r(x_0)$



then $\{w_i\}$ remains "admissible"

moreover

$$\left. \begin{aligned} m \leq v_i \leq w_i \leq u & \quad B_r(x_0) \\ \lim_{i \rightarrow \infty} v_i(x_0) = \lim_{i \rightarrow \infty} w_i(x_0) = u(x_0) & \\ \Delta w_i = 0 & \quad B_r(x_0) \end{aligned} \right\}$$

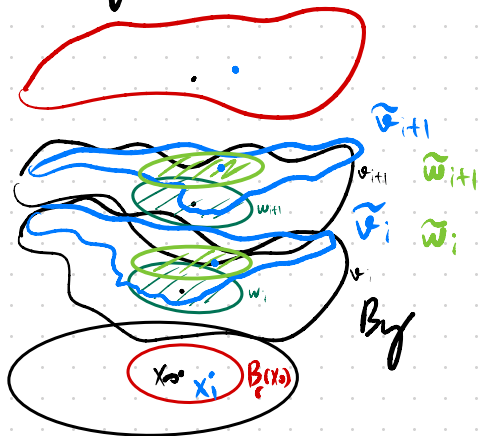
By uniform convergence of harmonic functions preserve "harmonicity"

and, by $W_{2,1}$ -Arzela interior gradient estimate we know $W := \lim_{i \rightarrow \infty} w_i$ remains harmonic in $B_r(x_0)$ up to subsequences

But we only know $W(x_0) = u(x_0)$ at this single point.

If we know $W = u$ in $B_r(x_0)$ we're happy

To see this, take another point $x_1 \in B_r(x_0)$, $x_1 \neq x_0$.



Repeat the same procedure as above just this time, take "maximizing sequence"

$$\{ \tilde{v}_i \} \text{ s.t. } \tilde{v}_i \geq w_i, \quad \forall i$$

then take $\{ \tilde{w}_i \}$ harmonic lifting of \tilde{v}_i in $B_r(x_0)$

$$m \leq v_i \leq w_i \leq \tilde{v}_i \leq \tilde{w}_i \leq U$$

$$\lim_{i \rightarrow \infty} \tilde{v}_i(x_1) = \lim_{i \rightarrow \infty} \tilde{w}_i(x_1) = u(x_1)$$

$$\lim_{i \rightarrow \infty} \tilde{v}_i(x_0) = \lim_{i \rightarrow \infty} \tilde{w}_i(x_0) = \tilde{w}(x_0) = w(x_0) = u(x_0)$$

By Ascoli-Arzelà, $\tilde{w} := \lim_{i \rightarrow \infty} \tilde{w}_i$ is another harmonic function in $B_r(x_0)$

$$\text{But } \begin{cases} \Delta \tilde{w} = \Delta w = 0 & B_r(x_0) \\ \tilde{w}(x_0) = w(x_0) \end{cases}$$

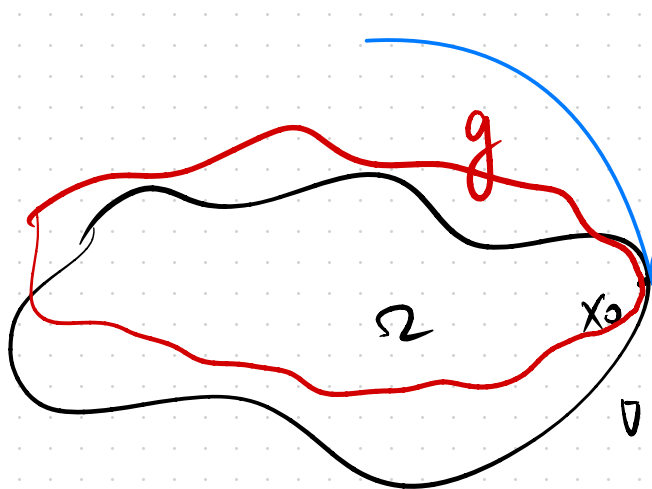
By **Strong Maximum Principle** we know $\tilde{w} = w$ in $B_r(x_0)$

In particular at x_1 , $u(x_1) = \tilde{w}(x_1) = w(x_1)$. But x_1 is arbitrary \square

Continuously Approach Boundary Data

let $g \in C(\partial\Omega)$

Can we show that u continuously approach Boundary Data g ?



Barrier $w_{x_0}(y) := \Gamma_{y_0}(y) - \underbrace{\Gamma_{y_0}(x_0 - y_0)}_{\text{constant}}$

so that

$$\begin{cases} \Delta w_{x_0}(x) \leq 0 & \Omega \\ w_{x_0}(x_0) = 0 \\ w_{x_0} \geq 0 & \Omega \end{cases}$$

$$\forall \varepsilon > 0, \exists \delta > 0 \text{ s.t. } |g(y) - g(x_0)| < \varepsilon \quad \forall |y - x_0| < \delta$$

if on the other hand $|y - x_0| \geq \delta$, $|g(y) - g(x_0)| \leq 2 \sup_{\partial\Omega} |g| = K$

$K w_{x_0}(y)$ this does not degenerate because $|y - x_0| \geq \delta$
large enough

$$\Rightarrow -\varepsilon - K w_{x_0}(y) \leq g(y) - g(x_0) \leq \varepsilon + K w_{x_0}(y)$$

$$\forall y \in \partial B_\delta$$

Our goal is to replace the above $g(y)$ with $u(y)$, and for $y \in \Omega$

$$\rightarrow \underbrace{-\varepsilon - K W_{x_0}(y) + g(x_0)}_{\text{this is subharmonic function below boundary data}} \leq u(y) \quad \forall y \in \Omega$$

using construction of u via Perron's method.

→ on the other hand,

$$v(y) \leq g(y) \leq \underbrace{g(x_0) + \varepsilon + K W_{x_0}(y)}_{\text{this is superharmonic}} \quad \forall y \in \partial \Omega$$

v is admissible subharmonic.

By **Maximum Principle**

$$v(y) \leq g(x_0) + \varepsilon + K W_{x_0}(y) \quad \forall y \in \Omega$$

But v is arbitrary admissible subharmonic function.
take sup gives u .

$$\rightarrow |u(y) - g(x_0)| \leq \varepsilon + K W_{x_0}(y). \quad \text{first send } y \rightarrow x_0, \text{ then } \varepsilon \downarrow 0.$$

we conclude $u \in C^{\alpha}(\Omega) \cap C^0(\bar{\Omega})$ □

Problem ③ Dirichlet problem for $\Delta u = f$ Poisson's Equation

$$\begin{cases} \Delta u = f & \Omega \\ u = g & \partial\Omega \end{cases} \quad \text{with } \Omega \text{ exterior Ball condition.}$$

What conditions on f can we make this problem well-posed?

morally, one want to decompose $u = v + w$.

where $\Delta w = f$ \mathbb{R}^n ,
for f compactly supported.

$$\begin{cases} \Delta v = 0 & \Omega \\ v = u - w & \partial\Omega \end{cases}$$

this has unique solution
from our Problem ②

It suffices to study the behavior of
 w s.t. $\Delta w = f$.

• Define **Newtonian Potential** $u(x) := \int_{\mathbb{R}^n} f(y) \tilde{P}(x-y) dy$

Why is this a reasonable choice?

Recall our derivation

$$\int_{\Omega} \Delta u \tilde{P} = \int_{\Omega} u \Delta \tilde{P}_{x_0} + \int_{\partial\Omega} \frac{\partial u}{\partial \nu} \tilde{P}_{x_0} ds - \int_{\partial\Omega} u \frac{\partial \tilde{P}}{\partial \nu} ds$$

$$\int_{\Omega} \underbrace{\Delta u}_{f''} \underbrace{\tilde{G}_{x_0}}_{\tilde{G}_{x_0}} = \int_{\Omega} u \underbrace{\Delta \tilde{G}_{x_0}}_{\delta_{x_0}} - \int_{\partial\Omega} u \frac{\partial \tilde{G}_{x_0}}{\partial \nu} ds$$

Also recall

$$\tilde{G}_{x_0} = \tilde{P}_{x_0} + \underbrace{h_{x_0}}_{\text{harmonic in } \Omega}$$

thus $u(x_0) = \underbrace{\int_{\Omega} f(y) \tilde{P}(x_0-y) dy}_{\text{Newtonian Potential}} + \text{something harmonic}$

we take Newtonian potential from here.

When is this well-defined? Recall $P(x) = C_n |x|^{2-n}$

→ when is $w \in C^0$? let $\text{supp}(f) \subseteq B_R$.

$$|w(x)| \leq \int_{B_R} |f| |P| \approx \|f\|_{L^p} \int_0^R r^{(2-n)p'} r^{n-1} dr$$

where $p' = \frac{p}{p-1}$ need $(2-n)\frac{p}{p-1} + n-1 > -1$

$$p > n/2$$

→ when is $w \in C^1$?

$$|Dw(x)| \leq \int_{B_R} |f| |DP| \approx \|f\|_{L^p} \int_0^R r^{(1-n)p'} r^{n-1} dr$$

need $(1-n)\frac{p}{p-1} + n-1 > -1$

$$p > n$$

But can we repeat the same procedure for $w \in C^2$? No!

For w to be C^2 we in fact need $f \in C_0^{\alpha}$ compact support for $0 < \alpha < 1$

Formula

$$\partial_j w(x) = \frac{\delta_{ij}}{n!} f(x) + \text{p.v.} (\partial_j T * f)(x) \quad (*)$$

where $\text{p.v.} (K * f)(x) := \lim_{\varepsilon \rightarrow 0} \int_{B_{\varepsilon}(x)} K(y) f(x-y) dy$ for some kernel K .

→ We can develop some theory for $K: \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}$ that is

- homogeneous of degree $-n$, i.e., $K(x) = |x|^{-n} g(\frac{x}{|x|})$
- $\int_{\partial B_1} K dS = 0$

assume $g: \partial B_1 \rightarrow \mathbb{R}$
Lipschitz

Indeed $\partial_j T$ satisfies such requirements for K .

→ Claim: for $f \in C_0^{\alpha}$, $Tf(x) := \text{p.v.} (K * f)(x)$ is continuous

proof notice $\int_{\mathbb{R}^n \setminus B_{\varepsilon}(0)} K = \int_{\mathbb{R}^n} \delta^n \cdot \delta^{n-1} \int_{\partial B_1} g dS = 0$

thus $\forall \varepsilon > 0$, $\int_{\mathbb{R}^n \setminus B_{\varepsilon}(0)} f(x-y) K(y) dy = \int_{\mathbb{R}^n \setminus B_{\varepsilon}(0)} (f(x-y) - f(x)) K(y) dy \leq C f_{C^{\alpha}} \int_{\mathbb{R}^n} r^{-\alpha-n} r^{n-1} dr < \infty$

thus $\|Tf\|_{\infty} \leq C$

moreover $\int_{B_{\varepsilon}(0)} (f(x-y) - f(x)) K(y) dy \leq C f_{C^{\alpha}} \int_0^{\varepsilon} r^{-\alpha-n+n-1} dr \leq C f_{C^{\alpha}} \varepsilon^{\alpha} \xrightarrow{\varepsilon \rightarrow 0} 0$
 $\Rightarrow Tf$ is continuous \square

uniformly in ε

→ We show the formula (*)

Proof take T_ε as our approximation for T

$$\begin{aligned} \text{then } \partial_j w^\varepsilon &= \partial_j (T_\varepsilon^* f) = (\partial_j T_\varepsilon)^* f = (\partial_j T^\varepsilon \chi_{B_\varepsilon})^* f + (\partial_j \tilde{T}_{B_\varepsilon^c}^\varepsilon)^* f \\ &= \left(\frac{\sum_j}{n |B_\varepsilon|} \chi_{B_\varepsilon} \right)^* f + (\partial_j \tilde{T}_{B_\varepsilon^c}^\varepsilon)^* f \\ &\xrightarrow{\varepsilon \rightarrow 0} \frac{\sum_j}{n} f(x) + \text{p.v.} (\partial_j T^* f)(x) \quad \square \end{aligned}$$

We've demonstrated that

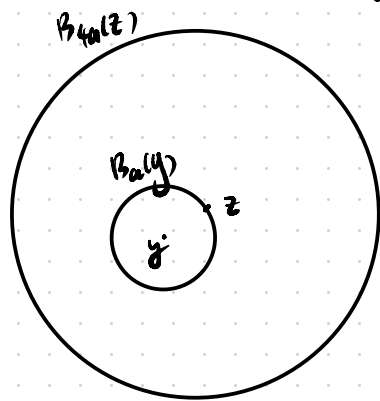
$$\text{for } f \in C^{0,\alpha} \Rightarrow w \in C^2$$

therefore our problem (3) admits $u \in C^2(\Omega) \cap C^0(\bar{\Omega})$ solution

BUT since $f \in C^{0,\alpha}$, why can't $u \in C^{2,\alpha}(\Omega)$???
let's check this!

→ Claim: for $f \in C^{0,\alpha}$ in fact $Tf(x) \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}(\Omega) \cap C^0(\bar{\Omega})$

Proof take arbitrary $y \neq z$. denote $a = |y - z|$



$$\begin{aligned} \text{then } Tf(z) &= \int_{\mathbb{R}^n} K(z-x) (f(x) - f(z)) dx \\ &= \underbrace{\int_{B_{4a}(z)} \dots}_{o(a^\alpha)} + \int_{B_{4a}(z)}^c K(z-x) (f(x) - f(z)) dx \end{aligned}$$

$$\begin{aligned} Tf(y) &= \int_{\mathbb{R}^n} K(y-x) (f(x) - f(y)) dx \\ &= \underbrace{\int_{B_a(y)} \dots}_{o(a^\alpha)} + \int_{B_{4a}(z) \setminus B_a(y)} K(y-x) (f(x) - f(z)) dx + \int_{B_{4a}(z)}^c K(y-x) (f(x) - f(z)) dx \end{aligned}$$

free to switch since away from y

Now subtract both.

$$|Tf(y) - Tf(z)| \leq \int_{B_{4a}(z)}^c |K(z-x) - K(y-x)| |f(x) - f(z)| dx$$

$o(a^\alpha)$ using the ball $B_{4a}(z)$

$$\lesssim \int_{C^{0,\alpha}} a \cdot \int_{4a}^\infty r^{-(n+1)} \cdot r^\alpha \cdot r^{n-1} dr = o(a^\alpha)$$

$\Rightarrow Tf \in C^{0,\alpha}$

